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VISION BASED CONTROL OF A MOBILE MANIPULATOR



LAP Lambert Academic Publishing Nov 2012, 2012. Taschenbuch. Condition: Neu. Neuware - In this book, control of a mobile manipulator system with a calibrated stereo rig is presented. Autonomous mobile manipulator equipped with a vision based target monitoring system can find and track a moving target and also manipulate it. The vision system is utilized to obtain task space feedback for mobile manipulator control. Using vision data, mobile platform (base) and manipulator are controlled with a hybrid visual servo controller...

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- Authored by Levent Çetin
- Released at 2012



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